

# ESTECO USERS' MEETING INDIA

# Leveraging scalable ROM, ML and AI through the synergy of VOLTA and romBOX



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## About OPTIMAD

Simulation-Driven vs Data-Driven

## romBOX & VOLTA

What is romBOX Synergy between romBOX and VOLTA

Conclusions

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# **ABOUT OPTIMAD**

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We use mathematical modelling and numerical simulation to describe products and processes and blend them with Machine Learning and Artificial Intelligence to value historical data and accelerate development times.

Our team is **talented, multi-disciplinary, and experienced**. They combine deep engineering knowledge and imagination to deliver innovation. We **cultivate competencies** and **we learn** together with our customers.



## People

Headcount (q4/22) 27

#### Strong scientific background

- computational geometry;
- numerical methods, scientific computing;
- data intelligence (reduced order models, ML, AI).

#### Industrial proficiency

- Computational fluid dynamics
- its integration in product development.



![](_page_4_Picture_10.jpeg)

![](_page_5_Picture_0.jpeg)

# mimic shape parameterization, mesh manipulation & morphing

![](_page_5_Picture_2.jpeg)

# romBOX

reduced order models & machine learning for simulation data intelligence

![](_page_5_Picture_6.jpeg)

Enabling the digital transformation of product development cycles and design processes

## References

**Transportation Industry** 

- Aerospace & Defence
- Automotive
- Naval
- Rail

Industrial Equipment Additive Manufacturing Food & Beverage Chemical Engineering

Biomedical

![](_page_6_Picture_8.jpeg)

romBOX & VOLTA

![](_page_6_Picture_10.jpeg)

![](_page_6_Picture_11.jpeg)

![](_page_6_Picture_12.jpeg)

ALSTOM

Guerbet Contrast for Life

![](_page_6_Picture_15.jpeg)

## **Agilent Technologies**

![](_page_6_Picture_17.jpeg)

![](_page_6_Picture_18.jpeg)

![](_page_6_Picture_19.jpeg)

![](_page_6_Picture_21.jpeg)

![](_page_6_Picture_22.jpeg)

LXOTIC

![](_page_6_Picture_23.jpeg)

STELL

![](_page_6_Picture_24.jpeg)

Adler Pelzer Group

GU C R Prima Power **C** Sidel

![](_page_6_Picture_27.jpeg)

# Simulation-driven vs Data-driven

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# **Simulation-driven product definition**

## State-of-the-art

![](_page_8_Figure_2.jpeg)

![](_page_8_Picture_3.jpeg)

# **Data-driven product definition**

## **Our vision**

![](_page_9_Figure_2.jpeg)

# Let's have a look at the data

## **Amount of data**

Simulation Driven without SPDM

![](_page_10_Picture_3.jpeg)

Simulation Driven with SPDM

![](_page_10_Picture_5.jpeg)

![](_page_10_Picture_6.jpeg)

#### Data Driven

![](_page_10_Picture_8.jpeg)

## Let's have a look at the data

## Data generation over time

**Simulation Driven** 

![](_page_11_Figure_3.jpeg)

![](_page_11_Figure_4.jpeg)

# Let's have a look at the data

## Lifetime of data

Simulation Driven	Data Driven	
<ul> <li>created and used for the duration of a task</li> </ul>	created during	
<ul> <li>conserved for process traceability and coherence</li> </ul>	<ul> <li>used for the du</li> </ul>	
	<ul> <li>conserved for p</li> </ul>	

• Can data be exploited **among projects**?

![](_page_12_Picture_4.jpeg)

#### ng a **task**

- duration of the **project for several tasks**
- or process traceability and coherence

# What is romBOX?

![](_page_13_Picture_1.jpeg)

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# a reduced order modelling & machine learning toolbox

#### Data-driven models

- Reduced Order Models
- ML, AI
- Multi-fidelity
- Data morphing

#### Geometry driven

- User-given parameterization
- Empiric parametrization
- Autoencoders

#### **Physics-driven models**

• by coupling solver

#### Any data

- Surface data
- Volume data
- Qol •
- Sensitivities

![](_page_14_Picture_18.jpeg)

![](_page_14_Picture_19.jpeg)

![](_page_14_Picture_20.jpeg)

![](_page_14_Picture_22.jpeg)

![](_page_14_Picture_23.jpeg)

## romBOX

## example, real-time aerodynamic predictions

![](_page_15_Picture_2.jpeg)

![](_page_15_Picture_3.jpeg)

#### geomtery

- DrivAer baseline
- mimic
- 8 design parameters

#### aerodynamic drag evalutation

- OpemFOAM
- 15M, simpleFOAM

#### ROM

- romBOX geometrical & data encoder
- RBF-NN regression model

#### Validation

- 20 unseen random configurations
- average L2 error on pressure distribution

![](_page_16_Figure_0.jpeg)

# Synergy between romBOX and VOLTA

![](_page_17_Picture_1.jpeg)

# Process, user and data management

### **Correct data management**

- Automatic annotation of data in the database
- Full control on data included in training

### **Traceability**

- of activity, i.e. who, what, when
- of results, models and data
  - data has been generated with which simulation model (annotation)
  - ROM model has been trained with which data (version tracking)
  - data has been generated when by who, with which method

![](_page_18_Picture_10.jpeg)

## **User management & roles**

- simulation experts are responsible for generating high-value (automatic) workflows
- application engineer exploit the simulation workflows to generate product relevant data
- domain experts train and publish ROMs to be exploited by other stackholders

## **Deployment for a streamlined user experience**

## Offline & online workflow as a project on VOLTA

- web technology on private or public cloud
- connect from anywhere
- handling of resources, distributed computing
- intuitive interface ٠
- collaborative
- allows experts to train a reliable ROM ۲
- allows non-expert users to exploit ROM autonomously

### Tasks

- single run
- DoE
- Optimization
- + data insight through VOLTA Advisor

scalable system

![](_page_19_Picture_15.jpeg)

# Deployment

### example: run an error-constrained model

![](_page_20_Figure_2.jpeg)

![](_page_20_Picture_3.jpeg)

i-fid

# Deployment

## example: retrieve results

![](_page_21_Figure_2.jpeg)

# Deployment

## example: retrieve results

![](_page_22_Figure_2.jpeg)

# Conclusions

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![](_page_24_Picture_0.jpeg)

# Thank you!

![](_page_24_Picture_2.jpeg)

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![](_page_24_Picture_4.jpeg)

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